



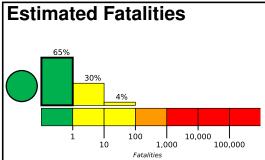


PAGER Version 3

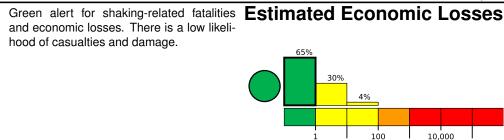
Created: 2 hours, 3 minutes after earthquake

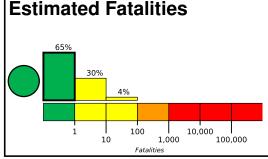
M 6.1, 31km ESE of Chaloem Phra Kiat, Thailand

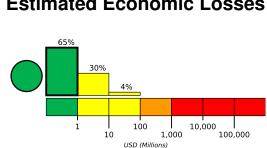
Origin Time: 2019-11-20 23:50:44 UTC (Thu 06:50:44 local) Location: 19.4512° N 101.3449° E Depth: 10.0 km



and economic losses. There is a low likeli-







Estimated Population Exposed to Earthquake Shaking

ESTIMATED POPULATION EXPOSURE (k=x1000)		_*	3,143k*	2,986k	127k	8k	0	0	0	0
ESTIMATED MODIFIED MERCALLI INTENSITY		I	11-111	IV	V	VI	VII	VIII	IX	X+
PERCEIVED SHAKING		Not felt	Weak	Light	Moderate	Strong	Very Strong	Severe	Violent	Extreme
POTENTIAL DAMAGE	Resistant Structures	None	None	None	V. Light	Light	Moderate	Mod./Heavy	Heavy	V. Heavy
	Vulnerable Structures	None	None	None	Light	Moderate	Mod./Heavy	Heavy	V. Heavy	V. Heavy

^{*}Estimated exposure only includes population within the map area.

Population Exposure

Mac Chai

Dck Kham Tai

Rong Kwa

Structures 101.8°W Louang Namtha

Luang Prabang

Ш

Ш

Van įviang

Muang Xay

Muana Nale

ainyabuli

population per 1 sq. km from Landscan

Overall, the population in this region resides in structures that are vulnerable to earthquake shaking, though resistant structures exist. The predominant vulnerable building types are informal (metal, timber, GI etc.) and unknown/miscellaneous types construction.

Historical Earthquakes

Date	Dist.	Mag.	Max	Shaking
(UTC)	(km)		MMI(#)	Deaths
1973-08-16	395	6.4	IX(20k)	1
2007-06-02	398	6.1	IX(2k)	3
1995-07-11	362	6.8	IX(3k)	11

Recent earthquakes in this area have caused secondary hazards such as landslides that might have contributed to losses.

Selected City Exposure

from GeoNames.org

MMI	City	Population
٧	Sainyabuli	14k
٧	Chaloem Phra Kiat	<1k
IV	Thung Chang	<1k
IV	Chiang Klang	13k
IV	Bo Kluea	<1k
IV	Tha Wang Pha	<1k
IV	Chiang Rai	79k
IV	Phrae	39k
Ш	Vientiane	197k
Ш	Luang Prabang	47k
Ш	Nong Khai	64k

bold cities appear on map.

(k = x1000)

PAGER content is automatically generated, and only considers losses due to structural damage. Limitations of input data, shaking estimates, and loss models may add uncertainty.